

Markov-switching processes



Model of structural change:

$$y_t - \mu_1 = \phi(y_{t-1} - \mu_1) + \varepsilon_t \quad t \leq t_0$$

$$y_t - \mu_2 = \phi(y_{t-1} - \mu_2) + \varepsilon_t \quad t > t_0$$

Questions:

- 1) How forecast with this model?
- 2) What caused change at t_0 ?
- 3) What is probability law for $\{y_t\}$?

$$s_t^* = 1 \quad t = 1, 2, \dots, t_0$$

$$s_t^* = 2 \quad t = t_0 + 1, t_0 + 2, \dots$$

$$y_t - \mu_{s_t^*} = \phi(y_{t-1} - \mu_{s_{t-1}^*}) + \varepsilon_t$$

Need: probability law for s_t^*

Markov chain:

$$P(s_t^* = j | s_{t-1}^* = i, s_{t-2}^* = k, \dots)$$

$$= P(s_t^* = j | s_{t-1}^* = i)$$

$$= p_{ij}$$

Transition from 1 to 2 is permanent

$$\Rightarrow p_{21} = 0$$

In general, if s_t is a Markov chain taking on one of the values $s_t = 1, 2, \dots, N$, let $p_{ij} = P(s_t = j | s_{t-1} = i)$. Collect in matrix $\mathbf{P} = [p_{ji}]$

$$\mathbf{P} = \begin{bmatrix} p_{11} & p_{21} & \cdots & p_{N1} \\ p_{12} & p_{22} & \cdots & p_{N2} \\ \vdots & \vdots & \cdots & \vdots \\ p_{1N} & p_{2N} & \cdots & p_{NN} \end{bmatrix}$$

Let $\xi_t = \mathbf{e}_i$ (the i th column of $\mathbf{I}_N$) when $s_t = i$. Then

$$\begin{aligned} E(\xi_{t+1} | \xi_t = \mathbf{e}_i) &= \begin{bmatrix} P(s_{t+1} = 1 | s_t = i) \\ P(s_{t+1} = 2 | s_t = i) \\ \vdots \\ P(s_{t+1} = N | s_t = i) \end{bmatrix} \\ &= \mathbf{P} \mathbf{e}_i \\ &= \mathbf{P} \xi_t \\ \xi_{t+1} &= \mathbf{P} \xi_t + \mathbf{v}_{t+1} \quad \mathbf{v}_{t+1} \sim m.d.s. \end{aligned}$$

More generally, suppose we had a set of observations $\Omega_t = \{\mathbf{y}_t, \mathbf{y}_{t-1}, \dots, \mathbf{y}_1\}$ that gave us an imperfect inference about s_t summarized as

$$\hat{\xi}_{t|t} = E(\xi_t | \Omega_t) = \begin{bmatrix} P(s_t = 1 | \Omega_t) \\ P(s_t = 2 | \Omega_t) \\ \vdots \\ P(s_t = N | \Omega_t) \end{bmatrix}$$

Then

$$\hat{\xi}_{t+1|t} = E(\xi_{t+1}|\Omega_t) = \mathbf{P}\hat{\xi}_{t|t}$$

(e.g., row j states that

$$\begin{aligned} P(s_{t+1} = j|\Omega_t) \\ = p_{1j}P(s_t = 1|\Omega_t) + p_{2j}P(s_t = 2|\Omega_t) \\ + \dots + p_{Nj}P(s_t = N|\Omega_t) \end{aligned}$$

Return to original example of interest:

$$y_t - \mu_{s_t^*} = \phi(y_{t-1} - \mu_{s_{t-1}^*}) + \varepsilon_t$$

$$\varepsilon_t \sim \text{i.i.d. } N(0, \sigma^2)$$

$$P(s_t^* = j | s_{t-1}^* = i) = p_{ij}^* \quad i, j = 1, 2$$

$$\{s_t^*\}_{t=1}^T \text{ independent of } \{\varepsilon_t\}_{t=1}^T$$

$$\Omega_t = \{y_t, y_{t-1}, \dots, y_1\}$$

Implication:

$$y_t | \Omega_{t-1}, s_t^*, s_{t-1}^* \sim N(\mu_{s_t^*} + \phi(y_{t-1} - \mu_{s_{t-1}^*}), \sigma^2)$$

Convenient to summarize $\{s_t^*, s_{t-1}^*\}$
with a single Markov chain:

$$s_t = 1 \quad \text{if } s_t^* = 1 \text{ and } s_{t-1}^* = 1$$

$$s_t = 2 \quad \text{if } s_t^* = 2 \text{ and } s_{t-1}^* = 1$$

$$s_t = 3 \quad \text{if } s_t^* = 1 \text{ and } s_{t-1}^* = 2$$

$$s_t = 4 \quad \text{if } s_t^* = 2 \text{ and } s_{t-1}^* = 2$$

$\xi_t = \mathbf{e}_i$ (ith column of $\mathbf{I}_4$) when $s_t = i$

$$\hat{\xi}_{t+1|t} = \mathbf{P} \hat{\xi}_{t|t}$$

$$\mathbf{P} = \begin{bmatrix} p_{11}^* & 0 & p_{11}^* & 0 \\ p_{12}^* & 0 & p_{12}^* & 0 \\ 0 & p_{21}^* & 0 & p_{21}^* \\ 0 & p_{22}^* & 0 & p_{22}^* \end{bmatrix}$$

$$p(y_t | s_t = 3, \Omega_{t-1})$$

$$= p(y_t | \mu_{s_t^*} = \mu_1, \mu_{s_{t-1}^*} = \mu_2, \Omega_{t-1})$$

$$= \frac{1}{\sqrt{2\pi} \sigma} \exp \left\{ \frac{-[y_t - \mu_1 - \phi(y_{t-1} - \mu_2)]^2}{2\sigma^2} \right\}$$

Collect the densities that might be associated with each of the $N = 4$ states in an $(N \times 1)$ vector

$$\boldsymbol{\eta}_t = \begin{bmatrix} p(y_t | s_t = 1, \Omega_{t-1}) \\ p(y_t | s_t = 2, \Omega_{t-1}) \\ \vdots \\ p(y_t | s_t = N, \Omega_{t-1}) \end{bmatrix}$$

Recall that

$$\mathbf{P}\hat{\boldsymbol{\xi}}_{t-1|t-1} = \begin{bmatrix} P(s_t = 1 | \Omega_{t-1}) \\ P(s_t = 2 | \Omega_{t-1}) \\ \vdots \\ P(s_t = N | \Omega_{t-1}) \end{bmatrix}$$

Thus

$$\boldsymbol{\eta}_t \odot \mathbf{P}\hat{\boldsymbol{\xi}}_{t-1|t-1} = \begin{bmatrix} p(y_t | s_t = 1, \Omega_{t-1}) P(s_t = 1 | \Omega_{t-1}) \\ p(y_t | s_t = 2, \Omega_{t-1}) P(s_t = 2 | \Omega_{t-1}) \\ \vdots \\ p(y_t | s_t = N, \Omega_{t-1}) P(s_t = N | \Omega_{t-1}) \end{bmatrix}$$

Summing the elements of this vector gives

$$\mathbf{1}'(\boldsymbol{\eta}_t \odot \mathbf{P}\hat{\boldsymbol{\xi}}_{t-1|t-1})$$

$$= \sum_{j=1}^N p(y_t, s_t = j | \Omega_{t-1})$$

$$= p(y_t | \Omega_{t-1}),$$

the conditional likelihood of t th observation.

The result of dividing the j th element of $(\boldsymbol{\eta}_t \odot \mathbf{P}\hat{\boldsymbol{\xi}}_{t-1|t-1})$ by the conditional likelihood is

$$\frac{p(y_t, s_t = j | \Omega_{t-1})}{p(y_t | \Omega_{t-1})} = P(s_t = j | y_t, \Omega_{t-1})$$

$$\frac{(\boldsymbol{\eta}_t \odot \mathbf{P}\hat{\boldsymbol{\xi}}_{t-1|t-1})}{\mathbf{1}'(\boldsymbol{\eta}_t \odot \mathbf{P}\hat{\boldsymbol{\xi}}_{t-1|t-1})} = \hat{\boldsymbol{\xi}}_{t|t}$$

$$\frac{(\boldsymbol{\eta}_t \odot \mathbf{P}\hat{\boldsymbol{\xi}}_{t-1|t-1})}{\mathbf{1}'(\boldsymbol{\eta}_t \odot \mathbf{P}\hat{\boldsymbol{\xi}}_{t-1|t-1})} = \hat{\boldsymbol{\xi}}_{t|t}$$

Iterative algorithm similar to Kalman filter:

Input for step t :

$$\hat{\boldsymbol{\xi}}_{t-1|t-1}$$

(an $N \times 1$ vector whose j th element is $P(s_{t-1} = j | y_{t-1}, y_{t-2}, \dots, y_1)$).

Output for step t :

$$\hat{\boldsymbol{\xi}}_{t|t}$$

Options for initial value $\hat{\xi}_{0|0}$:

(1) If Markov chain is ergodic,
use ergodic probabilities

$$\hat{\xi}_{0|0} = (\mathbf{A}'\mathbf{A})^{-1}\mathbf{A}'\mathbf{e}_{N+1}$$

$$\mathbf{A}_{(N+1) \times N} = \begin{bmatrix} \mathbf{I}_N - \mathbf{P} \\ \mathbf{1}' \end{bmatrix}$$

(2) Set $\hat{\xi}_{0|0} = \mathbf{p}$, a vector of free
parameters to be estimated by
maximum likelihood or Bayesian
methods along with the other
parameters.

(3) Set $\hat{\xi}_{0|0} = N^{-1}\mathbf{1}$.

(4) Set $\hat{\xi}_{0|0}$ based on prior beliefs.

Above assumed we knew parameters θ appearing in $\eta_t = [p(y_t|s_t = j, \Omega_{t-1}; \theta)]_{j=1}^N$ (in this case $\theta = (\phi, \mu_1, \mu_2, \sigma^2)'$) and $\mathbf{p}$ appearing in $\mathbf{P}$ (in this case $\mathbf{p} = (p_{11}, p_{22})'$).

However, as byproduct of step t of iteration we ended up calculating $p(y_t|\Omega_{t-1}; \theta, \mathbf{p})$ and so we've calculated log likelihood

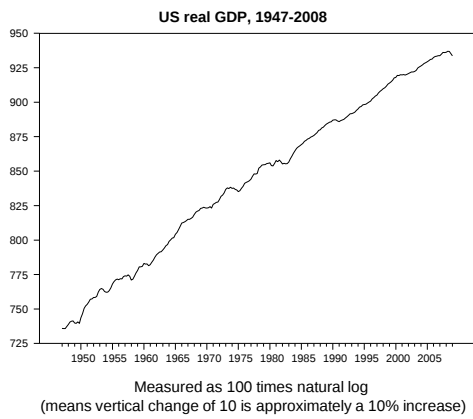
$$\mathcal{L}(\theta, \mathbf{p}) = \sum_{t=1}^T \log p(y_t|\Omega_{t-1}; \theta, \mathbf{p})$$

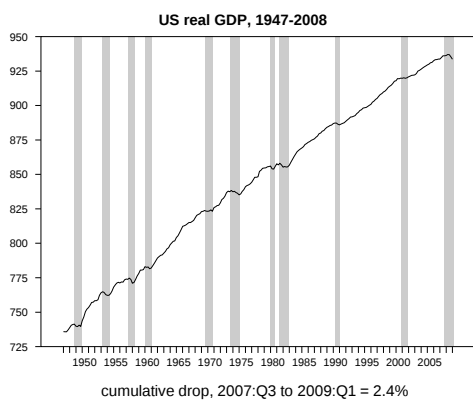
which can be maximized numerically with respect to θ and $\mathbf{p}$ by numerical methods.

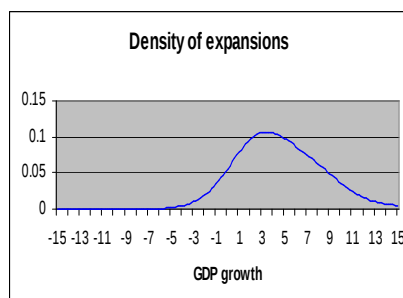
Note— during numerical search we'd want to be choosing λ_{11} and λ_{22} rather than p_{11} and p_{22} where

$$p_{11} = \frac{\lambda_{11}^2}{1 + \lambda_{11}^2}$$

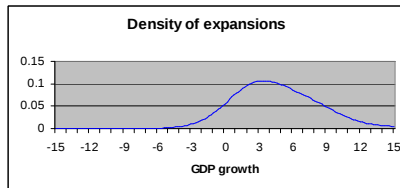
$$p_{22} = \frac{\lambda_{22}^2}{1 + \lambda_{22}^2}$$



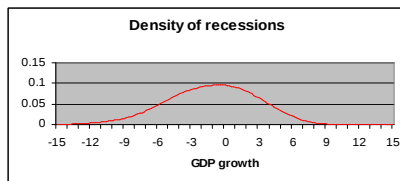




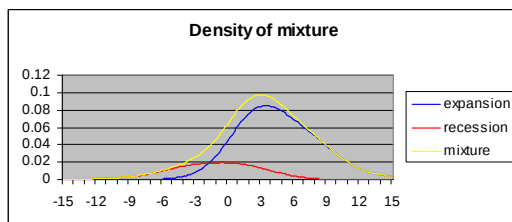
$\mu = 4.7$
 $\sigma = 3.5$

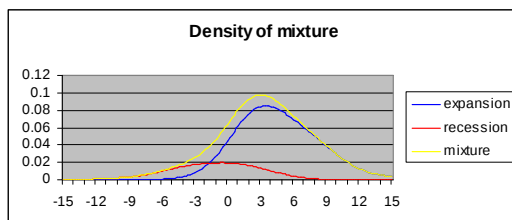


$\mu = 4.7$
 $\sigma = 3.5$

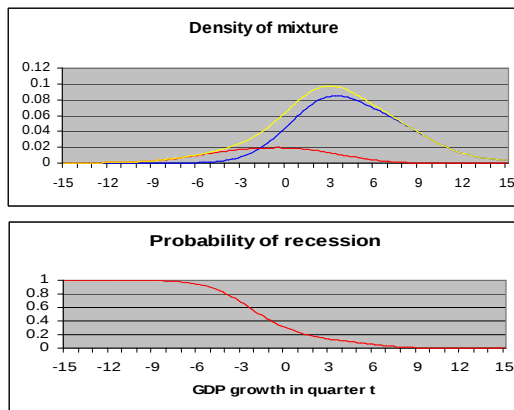


$\mu = -1.2$
 $\sigma = 3.5$



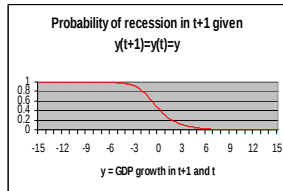
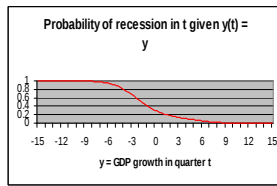


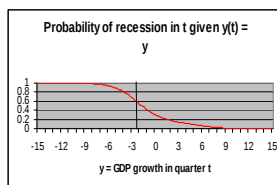
$$\begin{aligned} \Pr(S_i = 2 | y_i) &= \frac{\Pr(S_i = 2, y_i)}{f(y_i)} \\ &= \frac{\Pr(S_i = 2, y_i)}{\Pr(S_i = 1, y_i) + \Pr(S_i = 2, y_i)} \\ \Pr(S_i = 2, y_i) &= \Pr(S_i = 2) \cdot f(y_i | S_i = 2) \end{aligned}$$



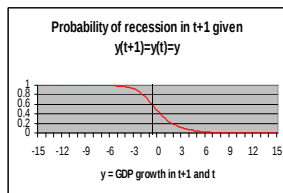
Prob(NBER expansion in $t + 1$ | NBER expansion in t)
 = $164/174 = 0.94$
 Prob(NBER contraction in $t + 1$ | NBER contraction in t)
 = $35/44 = 0.80$

$$\begin{aligned}
 \Pr(S_{t+1} = 2 \mid y_{t+1}, y_t) &= \frac{\Pr(S_{t+1} = 2, y_{t+1} \mid y_t)}{f(y_{t+1} \mid y_t)} \\
 &= \frac{\Pr(S_{t+1} = 2, y_{t+1} \mid y_t)}{\Pr(S_{t+1} = 1, y_{t+1} \mid y_t) + \Pr(S_{t+1} = 2, y_{t+1} \mid y_t)} \\
 \Pr(S_{t+1} = 2, y_{t+1} \mid y_t) &= \sum_{s=1}^2 \Pr(S_{t+1} = 2, S_t = s, y_{t+1} \mid y_t) \\
 \Pr(S_{t+1} = 2, S_t = s, y_{t+1} \mid y_t) &= \\
 \underbrace{\Pr(S_t = s \mid y_t)}_{\text{known from previous slide}} \cdot \underbrace{\Pr(S_{t+1} = 2 \mid S_t = s, y_t)}_{\substack{0.80 \text{ for } s=2 \\ 0.06 \text{ for } s=1}} \cdot \underbrace{f(y_{t+1} \mid S_{t+1} = 2, S_t = s, y_t)}_{\text{known from density of recessions}}
 \end{aligned}$$





Prob = 0.6
at $y = -2.2$



Prob = 0.6
At $y = -0.8$

Can also calculate "smoothed probability"

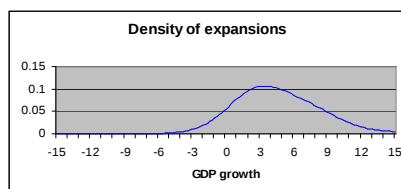
$$\Pr(S_t = 2 | y_t, y_{t+1})$$

Nonparametric summary of NBER labels:

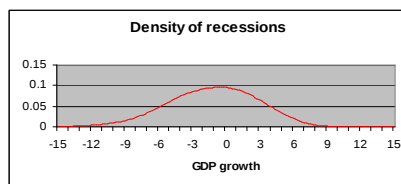
$f(y_t | S_t = 1)$ estimated nonparametrically

$\Pr(S_{t+1} = 1 | S_t = 1) = 0.94$

$\Pr(S_{t+1} = 2 | S_t = 2) = 0.80$



$\mu = 4.7$
 $\sigma = 3.5$



$\mu = -1.2$
 $\sigma = 3.5$

Could also approach parametrically:

$f(y_t | S_t = 1) \sim N(\mu_1, \sigma^2)$

$f(y_t | S_t = 2) \sim N(\mu_2, \sigma^2)$

$\Pr(S_{t+1} = 1 | S_t = 1) = p_{11}$

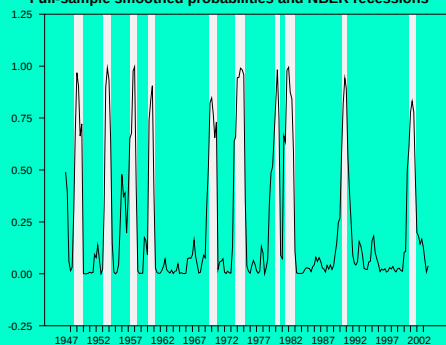
$\Pr(S_{t+1} = 2 | S_t = 2) = p_{22}$

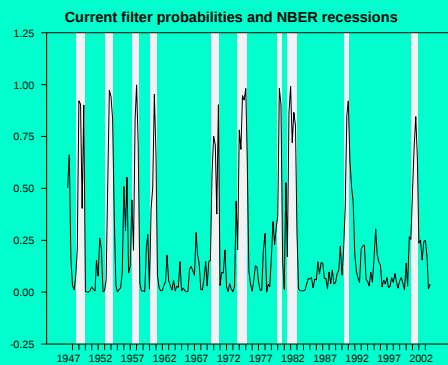
$$\Pr(S_{t+1} = 2, S_t = s, y_{t+1} | y_t) = \underbrace{\Pr(S_t = s | y_t)}_{\text{known from previous step}} \cdot \underbrace{\Pr(S_{t+1} = 2 | S_t = s, y_t)}_{\substack{p22 \text{ for } s=2 \\ p12 \text{ for } s=1}} \cdot \underbrace{f(y_{t+1} | S_{t+1} = 2, S_t = s, y_t)}_{N(\mu_s, \sigma^2)}$$

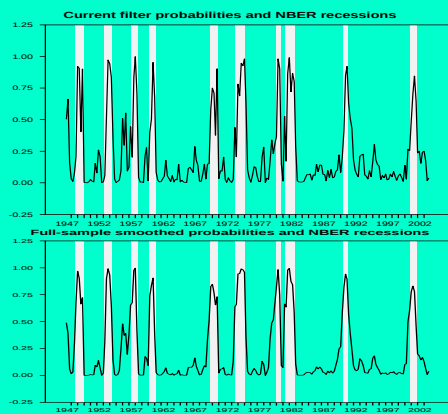
$$\begin{aligned} f(y_{t+1} | y_t) = & \Pr(S_{t+1} = 1, S_t = 1, y_{t+1} | y_t) + \\ & \Pr(S_{t+1} = 1, S_t = 2, y_{t+1} | y_t) + \\ & \Pr(S_{t+1} = 2, S_t = 1, y_{t+1} | y_t) + \\ & \Pr(S_{t+1} = 2, S_t = 2, y_{t+1} | y_t) \end{aligned}$$

Parameter	Estimated from NBER dates and GDP	Estimated from GDP alone
μ_1	4.73	4.62
μ_2	-1.19	-0.57
σ	3.47	3.35
p_{11}	0.94	0.92
p_{22}	0.80	0.74

Full-sample smoothed probabilities and NBER recessions



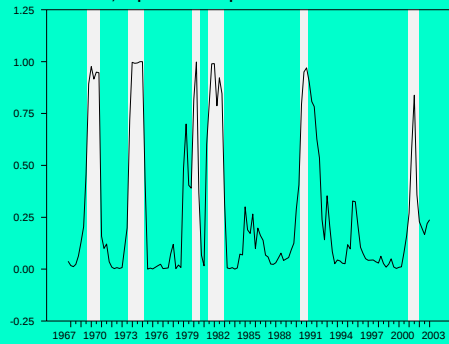




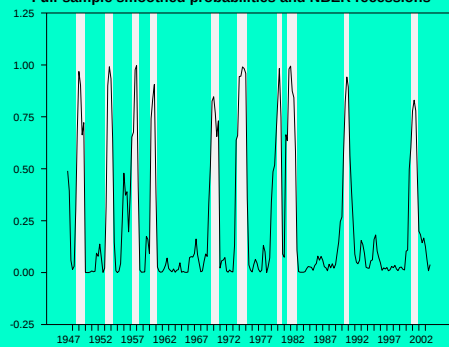
Another challenge:

- (1) Use only unrevised data as it was actually available at the time.
- (2) Use only data up through quarter t to estimate parameters and form inference for quarter $t - 1$.

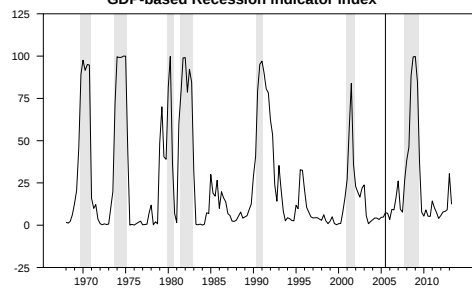
real-time release, 1-qtr smoothed probabilities and NBER recession:



Full-sample smoothed probabilities and NBER recessions



GDP-based Recession indicator index



Date of announcement	Announcement
Simulated (through June 2005)	
May 1970	recession began 1969:Q2
Aug 1971	recession ended 1970:Q4
May 1974	recession began 1973:Q4
Feb 1976	recession ended 1975:Q1
Nov 1979	recession began 1979:Q2
May 1981	recession ended 1980:Q2
Feb 1982	recession began 1981:Q2
Aug 1983	recession ended 1982:Q4
Feb 1991	recession began 1989:Q4
Feb 1993	recession ended 1991:Q4
Feb 2002	recession began 2001:Q1
Aug 2002	recession ended 2001:Q3
Actual real time (since July 2005)	
Jan 30, 2009	recession began 2007:Q4
Apr 30, 2010	recession ended 2009:Q2

General case:

$$\boldsymbol{\eta}_t = \begin{bmatrix} p(\mathbf{y}_t | s_t = 1, \Omega_{t-1}) \\ p(\mathbf{y}_t | s_t = 2, \Omega_{t-1}) \\ \vdots \\ p(\mathbf{y}_t | s_t = N, \Omega_{t-1}) \end{bmatrix}$$

$$p(\mathbf{y}_t | \Omega_{t-1}) = \mathbf{1}'(\boldsymbol{\eta}_t \odot \mathbf{P}\hat{\boldsymbol{\xi}}_{t-1|t-1})$$

$$\mathcal{L}(\mathbf{y}_1, \dots, \mathbf{y}_T; \boldsymbol{\theta}) = \sum_{t=1}^T \log p(\mathbf{y}_t | \Omega_{t-1})$$

Example: Dueker (JBES, 1997). AR(1) with Student t innovations whose degrees of freedom change with regime:

$$p(y_t | s_t = j, \Omega_{t-1}; \boldsymbol{\theta}) = \frac{\Gamma[(v_j + 1)/2]}{(\pi v_j)^{1/2} \Gamma(v_j/2) \sigma} \left[1 + \frac{(y_t - c - \phi y_{t-1})^2}{\sigma v_j} \right]^{-(v_j+1)/2}$$

$$\boldsymbol{\theta} = (c, \phi, \sigma, v_1, v_2)'$$

Example: Krolzig (*Markov-Switching Vector Autoregressions*, Springer 1997):
Gaussian VAR(1) with lag coefficients changing:

$$p(\mathbf{y}_t | s_t = j, \Omega_{t-1}, \boldsymbol{\theta}) = (2\pi)^{-n/2} |\boldsymbol{\Omega}|^{-1/2} \exp\left[-(1/2)(\mathbf{y}_t - \mathbf{c}_j - \boldsymbol{\Phi}_j \mathbf{y}_{t-1})' \boldsymbol{\Omega}^{-1} (\mathbf{y}_t - \mathbf{c}_j - \boldsymbol{\Phi}_j \mathbf{y}_{t-1})\right]$$

$$\boldsymbol{\theta} = (\mathbf{c}'_1, \mathbf{c}'_2, (\text{vec } \boldsymbol{\Phi}'_1)', (\text{vec } \boldsymbol{\Phi}'_2)', (\text{vech } \boldsymbol{\Omega})')'$$

Can also allow transition probabilities to be parametric function of exogenous or lagged dependent variables $\mathbf{z}_t$:

$$\mathbf{P} = [P(s_t = j | s_{t-1} = i, \mathbf{z}_t; \mathbf{p})]_{i,j=1}^N.$$

Example:

$$\mathbf{P} = \begin{bmatrix} \frac{\exp(\boldsymbol{\gamma}' \mathbf{z}_t)}{1 + \exp(\boldsymbol{\gamma}' \mathbf{z}_t)} & \frac{1}{1 + \exp(\boldsymbol{\delta}' \mathbf{z}_t)} \\ \frac{1}{1 + \exp(\boldsymbol{\gamma}' \mathbf{z}_t)} & \frac{\exp(\boldsymbol{\delta}' \mathbf{z}_t)}{1 + \exp(\boldsymbol{\delta}' \mathbf{z}_t)} \end{bmatrix}$$

$$\mathbf{p} = (\boldsymbol{\gamma}', \boldsymbol{\delta}')'$$

Testing the null hypothesis of no change in regime and choosing number of states N .

Example: Markov-switching regression

$$y_t = \mathbf{x}_t' \boldsymbol{\beta}_{s_t} + \sigma_{s_t} \varepsilon_t$$

$$s_t \in \{1, \dots, N\}$$

$$P(s_t = j | s_{t-1} = i) = p_{ij}$$

$$H_0: \boldsymbol{\beta}_j = \boldsymbol{\beta}, \sigma_j = \sigma \text{ for } j = 1, \dots, N$$

Problem: p_{ij} unidentified under H_0 .

Usual regularity conditions not satisfied, distribution of likelihood ratio test nonstandard.

(1) Smith, Naik, and Tsai (J. Econometrics, 2006): generalization of Akaike Information Criteria.

$$\begin{aligned}\boldsymbol{\theta} &= (\boldsymbol{\beta}'_1, \dots, \boldsymbol{\beta}'_N, \sigma_1, \dots, \sigma_N, \\ &\quad p_{ij, i=1, \dots, N; j=1, \dots, N-1})' \\ \mathcal{L}(\boldsymbol{\theta}) &= \sum_{t=1}^T \log p(y_t | \Omega_{t-1}; \boldsymbol{\theta}) \\ \Omega_{t-1} &= \{\mathbf{x}_t, y_{t-1}, \mathbf{x}_{t-1}, \dots, y_0, \mathbf{x}_0\} \\ \hat{\boldsymbol{\theta}}_{MLE} &= \arg \max \mathcal{L}(\boldsymbol{\theta}) \\ \hat{T}_i &= \sum_{t=1}^T P(s_t = i | \Omega_T; \hat{\boldsymbol{\theta}}_{MLE})\end{aligned}$$

Smith, Naik, and Tsai propose choosing model that minimizes

$$MSC = -2\mathcal{L}(\hat{\boldsymbol{\theta}}_{MLE}) + \sum_{i=1}^N \frac{\hat{T}_i(\hat{T}_i + Nk)}{\hat{T}_i - Nk - 2}$$

$$\boldsymbol{\beta}_i = (k \times 1)$$

MSC is estimate of information loss (Kullback-Leibler divergence) between $p(y_t|\Omega_{t-1}; \theta^*)$ and true density $g(y_t|\Omega_{t-1})$ for θ^* the KL-minimizing value of θ .

(2) Carrasco, Hu, and Ploberger (2013): test of null hypothesis of no switching for more general models.

Let $\ell_t = \log f(y_t|\Omega_{t-1}; \lambda)$ be the log likelihood under null hypothesis of no switching (e.g., $\lambda = (\beta', \sigma)'$ for previous example)

$$\mathbf{h}_t = \left. \frac{\partial \ell_t}{\partial \lambda} \right|_{\lambda = \hat{\lambda}_{MLE}}$$

H_A : first element of λ switches from latent Markov chain (CHP also propose tests for vector switches).

$\ell_t^{(1)} =$ first element of $\mathbf{h}_t$

$$\ell_t^{(2)} = \left. \frac{\partial^2 \ell_t}{\partial \lambda_1^2} \right|_{\lambda = \hat{\lambda}_{MLE}}$$

$$\gamma_t(\rho) = \ell_t^{(2)} + \left[\ell_t^{(1)} \right]^2 + 2 \sum_{s < t} \rho^{t-s} \ell_t^{(1)} \ell_s^{(1)}$$

ρ = unknown parameter characterizing persistence of Markov chain

(1) Regress $(1/2)\gamma_t(\rho)$ on $\mathbf{h}_t$ and calculate residuals $\hat{\varepsilon}_t(\rho)$.

(2) Calculate

$$C(\rho) = \frac{1}{2} \left[\max \left\{ 0, \frac{\sum_{t=1}^T \gamma_t(\rho)}{2 \sqrt{\sum_{t=1}^T [\hat{\varepsilon}_t(\rho)]^2}} \right\} \right]^2$$

(3) Find ρ^* over some range (e.g., $\rho \in [0.2, 0.8]$) to maximize $C(\rho)$ by numerical search.

(4) Bootstrap to see if $C(\rho^*)$ is statistically sig (i.e., generate data with no switching and $\lambda = \hat{\lambda}_{MLE}$, calculate $C(\rho^*)$ on each sample).
