

II. Vector autoregressions

A. Introduction

1. VARs as forecasting models

Suppose we want to forecast y_{1t}
based on:

$$y_{1,t-1}, y_{1,t-2}, \dots, y_{1,t-p}$$

$$y_{2,t-1}, y_{2,t-2}, \dots, y_{2,t-p}$$

⋮

$$y_{n,t-1}, y_{n,t-2}, \dots, y_{n,t-p}$$

deterministic functions of t

(1, t , $\cos(\pi t/6)$, seasonal dummies)

Let $\mathbf{y}_t = (y_{1t}, y_{2t}, \dots, y_{nt})'$
($n \times 1$)

$$\mathbf{x}_t = (1, \mathbf{y}'_{t-1}, \mathbf{y}'_{t-2}, \dots, \mathbf{y}'_{t-p})'$$

($k \times 1$)

$$k = np + 1$$

Suppose we consider linear forecast

$$\hat{y}_{1t|t-1} = \boldsymbol{\gamma}'_1 \mathbf{x}_t$$

Best forecast within linear class:

value of $\boldsymbol{\gamma}_1$ that minimizes

$$E(y_{1t} - \boldsymbol{\gamma}'_1 \mathbf{x}_t)^2$$

Proposition: If \mathbf{y}_t is covariance-stationary and $E(\mathbf{x}_t\mathbf{x}_t')$ is nonsingular, then optimal forecast uses

$$\gamma_1^* = E(\mathbf{x}_t\mathbf{x}_t')^{-1} E(\mathbf{x}_t y_t)$$

Definition: The optimal linear forecast,

$$\hat{y}_{1t|t-1} = \boldsymbol{\gamma}_1^{*'} \mathbf{x}_t,$$

is called the “population linear projection”
of y_{1t} on \mathbf{x}_t

Proposition: If \mathbf{y}_t is stationary and ergodic, then

$$\hat{\boldsymbol{\gamma}}_1 \xrightarrow{p} \boldsymbol{\gamma}_1^*$$

Proof: (Law of Large Numbers)

$$\hat{\boldsymbol{\gamma}}_1 = \left(T^{-1} \sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1} \left(T^{-1} \sum_{t=1}^T \mathbf{x}_t y_{1t} \right)$$

$$\xrightarrow{p} E(\mathbf{x}_t \mathbf{x}_t')^{-1} E(\mathbf{x}_t y_{1t})$$

If form separate forecasting equation for each element of \mathbf{y}_t and collect in vector,

$$y_{1t} = \boldsymbol{\gamma}'_1 \mathbf{x}_t + \varepsilon_{1t}$$

\vdots

$$y_{nt} = \boldsymbol{\gamma}'_n \mathbf{x}_t + \varepsilon_{nt}$$

$$\mathbf{y}_t = \boldsymbol{\Gamma}' \mathbf{x}_t + \boldsymbol{\varepsilon}_t$$

result is called vector autoregression:

$$\mathbf{y}_t = \mathbf{c} + \boldsymbol{\Phi}_1 \mathbf{y}_{t-1} + \boldsymbol{\Phi}_2 \mathbf{y}_{t-2} + \cdots + \boldsymbol{\Phi}_p \mathbf{y}_{t-p} + \boldsymbol{\varepsilon}_t$$

Above results imply we can consistently estimate coefficients for VAR by OLS equation by equation

$$\hat{\boldsymbol{\gamma}}'_1 = \left(\sum_{t=1}^T y_{1t} \mathbf{x}'_t \right) \left(\sum_{t=1}^T \mathbf{x}_t \mathbf{x}'_t \right)^{-1}$$

$(1 \times k)$

⋮

$$\hat{\boldsymbol{\gamma}}'_n = \left(\sum_{t=1}^T y_{nt} \mathbf{x}'_t \right) \left(\sum_{t=1}^T \mathbf{x}_t \mathbf{x}'_t \right)^{-1}$$

$(1 \times k)$

$$\hat{\boldsymbol{\Gamma}}' = \left(\sum_{t=1}^T \mathbf{y}_t \mathbf{x}'_t \right) \left(\sum_{t=1}^T \mathbf{x}_t \mathbf{x}'_t \right)^{-1}$$

$(n \times k)$

$$\hat{\boldsymbol{\Gamma}}' = \left[\hat{\mathbf{c}} \quad \hat{\boldsymbol{\Phi}}_1 \quad \hat{\boldsymbol{\Phi}}_2 \quad \cdots \quad \hat{\boldsymbol{\Phi}}_p \right]$$

II. Vector autoregressions

A. Introduction

1. VARs as forecasting models
2. Gaussian VARs as data-generating process

Consider the following process whereby the $(n \times 1)$ vector \mathbf{y}_t might have been generated:

$$\mathbf{y}_t = \mathbf{c} + \mathbf{\Phi}_1 \mathbf{y}_{t-1} + \mathbf{\Phi}_2 \mathbf{y}_{t-2} + \cdots + \mathbf{\Phi}_p \mathbf{y}_{t-p} + \boldsymbol{\varepsilon}_t$$

$$\boldsymbol{\varepsilon}_t \sim N(\mathbf{0}, \boldsymbol{\Omega})$$

log likelihood:

$$\begin{aligned}\mathcal{L} &= \log p(\mathbf{y}_1, \mathbf{y}_2, \dots, \mathbf{y}_T | \mathbf{y}_0, \mathbf{y}_{-1}, \dots, \mathbf{y}_{-p+1}, \boldsymbol{\theta}) \\ &= \sum_{t=1}^T \log p(\mathbf{y}_t | \mathbf{y}_{t-1}, \dots, \mathbf{y}_{t-p}, \boldsymbol{\theta}) \\ &= -(Tn/2) \log(2\pi) - (T/2) \log |\boldsymbol{\Omega}| \\ &\quad - (1/2) \sum_{t=1}^T \boldsymbol{\varepsilon}_t' \boldsymbol{\Omega}^{-1} \boldsymbol{\varepsilon}_t\end{aligned}$$

$$\begin{aligned}\boldsymbol{\varepsilon}_t &= \mathbf{y}_t - \mathbf{c} - \boldsymbol{\Phi}_1 \mathbf{y}_{t-1} - \boldsymbol{\Phi}_2 \mathbf{y}_{t-2} - \dots - \boldsymbol{\Phi}_p \mathbf{y}_{t-p} \\ &= \mathbf{y}_t - \boldsymbol{\Gamma}' \mathbf{x}_t\end{aligned}$$

$\boldsymbol{\theta}$ = vector containing elements of

$$\mathbf{c}, \boldsymbol{\Phi}_1, \boldsymbol{\Phi}_2, \dots, \boldsymbol{\Phi}_p, \boldsymbol{\Omega}$$

Classical results for VARs:

(1) The MLE of Γ is OLS

equation by equation:

$$\hat{\Gamma}'_{(n \times k)} = \left(\sum_{t=1}^T \mathbf{y}_t \mathbf{x}'_t \right) \left(\sum_{t=1}^T \mathbf{x}_t \mathbf{x}'_t \right)^{-1}$$

(2) The MLE of Ω is average product of residuals:

$$\hat{\Omega}_{(n \times n)} = T^{-1} \sum_{t=1}^T \hat{\boldsymbol{\varepsilon}}_t \hat{\boldsymbol{\varepsilon}}_t'$$

$$\hat{\boldsymbol{\varepsilon}}_{(n \times 1)}_t = \mathbf{y}_t - \hat{\Gamma}' \mathbf{x}_t$$

(3) The asymptotic distribution of

$$\hat{\boldsymbol{\gamma}} = \text{vec}(\hat{\boldsymbol{\Gamma}}) = (\hat{\boldsymbol{\gamma}}_1', \hat{\boldsymbol{\gamma}}_2', \dots, \hat{\boldsymbol{\gamma}}_n')'$$

$(nk \times 1)$

is given by

$$\sqrt{T} (\hat{\boldsymbol{\gamma}} - \boldsymbol{\gamma}) \xrightarrow{L} N(\mathbf{0}, \boldsymbol{\Omega} \otimes \mathbf{M})$$

$$\mathbf{M} = \text{plim} \left(T^{-1} \sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1}$$

$$\boldsymbol{\Omega} \otimes \mathbf{M} = \begin{bmatrix} \sigma_{11} \mathbf{M} & \cdots & \sigma_{1n} \mathbf{M} \\ \vdots & \ddots & \vdots \\ \sigma_{n1} \mathbf{M} & \cdots & \sigma_{nn} \mathbf{M} \end{bmatrix}$$

II. Vector autoregressions

A. Introduction

1. VARs as forecasting models
2. Gaussian VARs as data-generating process
3. VARs as ad hoc dynamic structural models

Example:

f_t = federal funds rate

y_t = output growth

π_t = inflation

m_t = money growth rate

Represent Fed behavior by

$$f_t = \alpha_0 + \alpha_1 y_t + \alpha_2 \pi_t + \alpha_3 f_{t-1} \\ + \alpha_4 y_{t-1} + \alpha_5 \pi_{t-1} + \alpha_6 m_{t-1} + v_t$$

Fed responds to current output
and inflation but not current
money growth

$$\mathbf{y}_t = (f_t, y_t, \pi_t, m_t)' \quad \mathbf{B}_0 \mathbf{y}_t = \mathbf{k} + \mathbf{B}_1 \mathbf{y}_{t-1} + \mathbf{v}_t$$

$$\mathbf{B}_0 = \begin{bmatrix} 1 & -\alpha_1 & -\alpha_2 & 0 \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \end{bmatrix}$$

$$\mathbf{B}_1 = \begin{bmatrix} \alpha_3 & \alpha_4 & \alpha_5 & \alpha_6 \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \end{bmatrix}$$

If $\mathbf{v}_t \sim$ i.i.d. $N(\mathbf{0}, \mathbf{D})$, log likelihood is

$$\begin{aligned}\mathcal{L} &= \log f(\mathbf{y}_1, \mathbf{y}_2, \dots, \mathbf{y}_T | \mathbf{y}_0, \mathbf{y}_{-1}, \dots, \mathbf{y}_{-p+1}, \boldsymbol{\theta}) \\ &= -(Tn/2) \log(2\pi) - (T/2) \log |\mathbf{D}| \\ &\quad + T \log |\mathbf{B}_0| - (1/2) \sum_{t=1}^T \mathbf{v}_t' \mathbf{D}^{-1} \mathbf{v}_t\end{aligned}$$

$$\mathbf{D} = E(\mathbf{v}_t \mathbf{v}_t')$$

$$\begin{aligned}\mathbf{v}_t &= \mathbf{B}_0 \mathbf{y}_t - \mathbf{k} - \mathbf{B}_1 \mathbf{y}_{t-1} - \mathbf{B}_2 \mathbf{y}_{t-2} - \\ &\quad \dots - \mathbf{B}_p \mathbf{y}_{t-p}\end{aligned}$$

$\boldsymbol{\theta}$ = vector containing elements of

$$\mathbf{k}, \mathbf{B}_0, \mathbf{B}_1, \dots, \mathbf{B}_p, \mathbf{D}$$

If model is just-identified, the MLE's

$$\hat{\mathbf{k}}, \hat{\mathbf{B}}_0, \hat{\mathbf{B}}_1, \dots, \hat{\mathbf{B}}_p, \hat{\mathbf{D}}$$

are transformations of the VAR MLE's

$$\hat{\mathbf{c}}, \hat{\Phi}_1, \hat{\Phi}_2, \dots, \hat{\Phi}_p, \hat{\Omega}$$

II. Vector autoregressions

A. Introduction

B. Normal-Wishart priors for VARs

For univariate regression,

$$y_t = \mathbf{x}'_t \boldsymbol{\beta} + \varepsilon_t$$

$$\varepsilon_t \sim N(0, \sigma^2)$$

we used Normal-Gamma for
natural conjugate prior:

$$\boldsymbol{\beta} | \sigma^2 \sim N(\mathbf{m}, \sigma^2 \mathbf{M})$$

$$\sigma^{-2} \sim \Gamma(N, \lambda)$$

From asymptotic distribution of MLE,

$$\sqrt{T} (\hat{\gamma} - \gamma) \xrightarrow{L} N(\mathbf{0}, \mathbf{\Omega} \otimes \mathbf{M})$$

$$\mathbf{M} = \text{plim} \left(T^{-1} \sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1},$$

we might guess that natural conjugate prior is of the form

$$\gamma | \mathbf{\Omega} \sim N(\mathbf{m}, \mathbf{\Omega} \otimes \mathbf{M})$$

\mathbf{m} = prior guess for γ

\mathbf{M} summarizes confidence

Prior for Ω :

univariate regression

$$\sigma^2 = E(\varepsilon_t^2)$$

$$Z_i \sim N(0, \lambda^{-1})$$

$$W = (Z_1^2 + Z_2^2 + \dots + Z_N^2)$$

W has gamma distribution

with parameters N, λ

$$\sigma^{-2} \sim \Gamma(N, \lambda)$$

Vector autoregression:

$$\mathbf{\Omega} = E(\boldsymbol{\varepsilon}_t \boldsymbol{\varepsilon}_t')$$

$$\mathbf{z}_i \sim N(\mathbf{0}, \mathbf{\Lambda}^{-1})$$

$n \times 1$

$$\mathbf{W} = (\mathbf{z}_1 \mathbf{z}_1' + \mathbf{z}_2 \mathbf{z}_2' + \cdots + \mathbf{z}_N \mathbf{z}_N')$$

\mathbf{W} has Wishart distribution

with parameters $N, \mathbf{\Lambda}$

$$\mathbf{\Omega}^{-1} \sim W(N, \mathbf{\Lambda})$$

$$\mathbf{W} \sim W(N, \Lambda) \Rightarrow$$

$$p(\mathbf{w}) = c |\Lambda|^{N/2} |\mathbf{w}|^{(N-n-1)/2} \exp \left[-\frac{1}{2} \text{tr}(\mathbf{w} \Lambda) \right]$$

$$c = \left[2^{Nn/2} \pi^{n(n-1)/4} \prod_{j=1}^n \Gamma \left(\frac{N+1-j}{2} \right) \right]^{-1}$$

so prior takes the form

$$p(\mathbf{\Omega}^{-1}) \propto |\mathbf{\Omega}|^{-(N-n-1)/2} \exp \left[-\frac{1}{2} \text{tr}(\mathbf{\Omega}^{-1} \Lambda) \right]$$

$$\mathbf{y}_t = \mathbf{\Gamma}' \mathbf{X}_t + \boldsymbol{\varepsilon}_t$$

$n \times 1$ $n \times k$ $k \times 1$ $n \times 1$

$$\boldsymbol{\gamma} = \text{vec}(\mathbf{\Gamma})$$

$nk \times 1$

first k components of $\boldsymbol{\gamma} =$
coefficients to explain y_{1t}

Prior for $\boldsymbol{\gamma}$:

univariate regression

$$\boldsymbol{\beta} | \sigma^{-2} \sim N(\mathbf{m}, \sigma^2 \mathbf{M})$$

vector autoregression

$$\boldsymbol{\gamma} | \boldsymbol{\Omega}^{-1} \sim N \left(\begin{array}{c} \mathbf{m}, \quad \boldsymbol{\Omega} \otimes \mathbf{M} \\ nk \times 1 \quad n \times n \quad k \times k \end{array} \right)$$

$$p(\boldsymbol{\gamma} | \boldsymbol{\Omega}^{-1}) \propto (2\pi)^{-nk/2} |\boldsymbol{\Omega}|^{-k/2}$$

$$\exp \left[-\frac{1}{2} (\boldsymbol{\gamma} - \mathbf{m})' (\boldsymbol{\Omega} \otimes \mathbf{M})^{-1} (\boldsymbol{\gamma} - \mathbf{m}) \right]$$

$$\begin{aligned}
p(\boldsymbol{\gamma}, \boldsymbol{\Omega}^{-1} | \mathbf{Y}) &\propto p(\boldsymbol{\gamma}, \boldsymbol{\Omega}^{-1}, \mathbf{Y}) \\
&= p(\mathbf{Y} | \boldsymbol{\gamma}, \boldsymbol{\Omega}^{-1}) p(\boldsymbol{\gamma} | \boldsymbol{\Omega}^{-1}) p(\boldsymbol{\Omega}^{-1}) \\
&\propto |\boldsymbol{\Omega}|^{-T/2} \exp \\
&\quad \left[-\frac{1}{2} \sum (\mathbf{y}_t - \boldsymbol{\Gamma}' \mathbf{x}_t)' \boldsymbol{\Omega}^{-1} (\mathbf{y}_t - \boldsymbol{\Gamma}' \mathbf{x}_t) \right] \\
&|\boldsymbol{\Omega}|^{-k/2} \exp \left[-\frac{1}{2} (\boldsymbol{\gamma} - \mathbf{m})' (\boldsymbol{\Omega} \otimes \mathbf{M})^{-1} (\boldsymbol{\gamma} - \mathbf{m}) \right] \\
&|\boldsymbol{\Omega}|^{-(N-n-1)/2} \exp \left[-\frac{1}{2} \text{tr}(\boldsymbol{\Omega}^{-1} \boldsymbol{\Lambda}) \right]
\end{aligned}$$

After a lot of algebra, this can be rewritten as

$$p(\boldsymbol{\gamma}, \boldsymbol{\Omega}^{-1} | \mathbf{Y}) \propto |\boldsymbol{\Omega}|^{-k/2} \exp \left[-\frac{1}{2} (\boldsymbol{\gamma} - \mathbf{m}^*)' (\boldsymbol{\Omega} \otimes \mathbf{M}^*)^{-1} (\boldsymbol{\gamma} - \mathbf{m}^*) \right]$$

$$|\boldsymbol{\Omega}|^{-(T+N-n-1)/2} \exp \left[-\frac{1}{2} \text{tr}(\boldsymbol{\Omega}^{-1} \boldsymbol{\Lambda}^*) \right]$$

$$\text{i.e., } \boldsymbol{\gamma} | \boldsymbol{\Omega}^{-1}, \mathbf{Y} \sim N(\mathbf{m}^*, \boldsymbol{\Omega} \otimes \mathbf{M}^*)$$

$$\boldsymbol{\Omega}^{-1} | \mathbf{Y} \sim W(T + N, \boldsymbol{\Lambda}^*)$$

$$\boldsymbol{\gamma} | \boldsymbol{\Omega}^{-1}, \mathbf{Y} \sim N(\mathbf{m}^*, \boldsymbol{\Omega} \otimes \mathbf{M}^*)$$

$$\mathbf{M}^* = \left(\mathbf{M}^{-1} + \sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1}$$

$$\begin{aligned} \mathbf{m}^* &= \left(\mathbf{I}_n \otimes \mathbf{M}^* \mathbf{M}^{-1} \right) \mathbf{m} \\ &\quad + \left(\mathbf{I}_n \otimes \mathbf{M}^* \sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right) \hat{\boldsymbol{\gamma}} \end{aligned}$$

$$\hat{\boldsymbol{\gamma}} = \text{vec}(\hat{\boldsymbol{\Gamma}})$$

$$\hat{\boldsymbol{\Gamma}} = \left(\sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1} \left(\sum_{t=1}^T \mathbf{x}_t \mathbf{y}_t' \right)$$

Diffuse prior: $\mathbf{M}^{-1} = \mathbf{0}$

$$\boldsymbol{\gamma} | \boldsymbol{\Omega}^{-1}, \mathbf{Y} \sim N\left(\hat{\boldsymbol{\gamma}}, \boldsymbol{\Omega} \otimes \left[\sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t'\right]^{-1}\right)$$

Estimate i th equation of VAR by OLS

$$\hat{\boldsymbol{\gamma}}_i = \left(\sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t'\right)^{-1} \left(\sum_{t=1}^T \mathbf{x}_t y_{it}\right)$$

(corresponds to elements $k(i-1) + 1$
through ki of $\hat{\boldsymbol{\gamma}}$)

$\hat{\boldsymbol{\gamma}}_i$ is posterior mean of $\boldsymbol{\gamma}_i$ and

$\sigma_{ii} \left(\sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t'\right)^{-1}$ is posterior

variance (conditional on $\boldsymbol{\Omega}$)

$$\mathbf{\Omega}^{-1} | \mathbf{Y} \sim W(T + N, \mathbf{\Lambda}^*)$$

$$\mathbf{\Lambda}^* = \mathbf{\Lambda} + \hat{\mathbf{S}} + \mathbf{Q}$$

$$\hat{\mathbf{S}} = \sum_{t=1}^T \left(\mathbf{y}_t - \hat{\mathbf{\Gamma}}' \mathbf{x}_t \right) \left(\mathbf{y}_t - \hat{\mathbf{\Gamma}}' \mathbf{x}_t \right)'$$

$$\mathbf{Q} = \mathbf{V}' \left(\sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right) \mathbf{M}^* \mathbf{M}^{-1} \mathbf{V}$$

$$\text{vec} \begin{pmatrix} \mathbf{V} \\ k \times n \end{pmatrix} = \mathbf{m} - \hat{\mathbf{y}}$$

Diffuse prior: $N = 0, \mathbf{M}^{-1} = \mathbf{0}, \mathbf{\Lambda} = \mathbf{0}$

Diffuse prior:

$$\mathbf{\Omega}^{-1} | \mathbf{Y} \sim W(T, \hat{\mathbf{S}})$$

$$\boldsymbol{\gamma} | \mathbf{\Omega}^{-1}, \mathbf{Y} \sim N\left(\hat{\boldsymbol{\gamma}}, \mathbf{\Omega} \otimes \left[\sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t'\right]^{-1}\right)$$

To generate a draw from the posterior distribution of $(\boldsymbol{\gamma}, \boldsymbol{\Omega}^{-1})$ with a diffuse prior:

(1) Estimate i th equation of VAR by OLS for $i = 1, 2, \dots, n$

$$\hat{\boldsymbol{\gamma}}_i = \left(\sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1} \left(\sum_{t=1}^T \mathbf{x}_t y_{it} \right)$$

$$\mathbf{M}^* = \left(\sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1}$$

(2) Calculate residual of i th equation and sum of outer products of residuals:

$$\hat{\boldsymbol{\varepsilon}}_{it} = y_{it} - \hat{\boldsymbol{\gamma}}_i' \mathbf{X}_t$$

$$\hat{\mathbf{S}}_{n \times n} = \sum_{t=1}^T \hat{\boldsymbol{\varepsilon}}_t \hat{\boldsymbol{\varepsilon}}_t'$$

(3) Generate an artificial sample of size

T of $(n \times 1)$ vector $\mathbf{z}_{\tilde{t}}$ where $\mathbf{z}_{\tilde{t}} \sim N\left(\mathbf{0}, \hat{\mathbf{S}}^{-1}\right)$

and calculate the $(n \times n)$ matrix

$$\mathbf{w} = \sum_{\tilde{t}=1}^T \mathbf{z}_{\tilde{t}} \mathbf{z}_{\tilde{t}}'$$

(4) Set $\Omega = \mathbf{W}^{-1}$.

(5) Generate a draw for γ from a $N(\hat{\gamma}, \Omega \otimes \mathbf{M}^*)$ distribution.

The values of Ω from step (4) and γ from step (5) represent a single draw from the posterior distribution. To generate a Monte Carlo sample of D draws, repeat steps (3)-(5) D times.

To get standard errors on impulse-response functions, for each draw calculate the impulse-response function implied by that value of γ .

Usual procedure: Ω is fixed at $T^{-1}\hat{\mathbf{S}}$ for all draws = asymptotic classical distribution or approximation to Bayesian distribution with diffuse prior.

Example of using a non-diffuse prior
(Del Negro and Schorfheide, 2002).

They use a log-linearization of a real business cycle model to get theoretical values for VAR parameters:

$$\mathbf{y}_t = \mathbf{\Gamma}'_0 \mathbf{x}_t + \boldsymbol{\varepsilon}_t$$

$$E(\boldsymbol{\varepsilon}_t \boldsymbol{\varepsilon}'_t) = \boldsymbol{\Omega}_0$$

Suppose we had an artificial “sample” of observations $\{\tilde{\mathbf{y}}_{\tilde{t}}\}_{\tilde{t}=-p+1}^{\tilde{T}}$ and base \mathbf{m} , \mathbf{M} , N , and $\mathbf{\Lambda}$ on a diffuse inference from this sample:

$$\mathbf{M} = \left(\sum_{\tilde{t}=1}^{\tilde{T}} \tilde{\mathbf{x}}_{\tilde{t}} \tilde{\mathbf{x}}_{\tilde{t}}' \right)^{-1}$$

$$\tilde{\mathbf{\Gamma}} = \mathbf{M} \sum_{\tilde{t}=1}^{\tilde{T}} \tilde{\mathbf{x}}_{\tilde{t}} \tilde{\mathbf{y}}_{\tilde{t}}'$$

$$\mathbf{m} = \mathbf{vec}(\tilde{\mathbf{\Gamma}})$$

$$N = \tilde{T}$$

$$\mathbf{\Lambda} = \sum_{\tilde{t}=1}^{\tilde{T}} \left(\mathbf{y}_{\tilde{t}} - \tilde{\mathbf{\Gamma}}' \mathbf{x}_{\tilde{t}} \right) \left(\mathbf{y}_{\tilde{t}} - \tilde{\mathbf{\Gamma}}' \mathbf{x}_{\tilde{t}} \right)'$$

We could then use these values of \mathbf{m} , \mathbf{M} , N , and $\mathbf{\Lambda}$ together with the actual observed data $\{\mathbf{y}_t\}_{t=-p+1}^T$ to form a posterior inference using the earlier formulas, where choice of \tilde{T} would reflect how much weight to put on the “real business cycle prior.”

Actually, we can use the RBC's implied values of Γ_0 and Ω_0 not just to simulate a few observations, but we can use them to calculate analytically the moments:

$$E(\tilde{\mathbf{x}}_t \tilde{\mathbf{x}}_t') = \mathbf{A}_0$$

$$E(\tilde{\mathbf{x}}_t \tilde{\mathbf{y}}_t') = \mathbf{B}_0$$

$$E(\tilde{\mathbf{y}}_t \tilde{\mathbf{y}}_t') = \mathbf{C}_0$$

where \mathbf{A}_0 , \mathbf{B}_0 and \mathbf{C}_0 are functions of Γ_0 and Ω_0 .

$$\mathbf{M} = \left(\sum_{\tilde{t}=1}^{\tilde{T}} \tilde{\mathbf{x}}_{\tilde{t}} \tilde{\mathbf{x}}_{\tilde{t}}' \right)^{-1} \leftrightarrow (\tilde{\mathbf{T}} \mathbf{A}_0)^{-1}$$

$$\tilde{\mathbf{\Gamma}} = \mathbf{M} \sum_{\tilde{t}=1}^{\tilde{T}} \tilde{\mathbf{x}}_{\tilde{t}} \tilde{\mathbf{y}}_{\tilde{t}}' \leftrightarrow \mathbf{A}_0^{-1} \mathbf{B}_0$$

$$\mathbf{m} = \mathbf{vec}(\tilde{\mathbf{\Gamma}})$$

$$N = \tilde{T}$$

$$\begin{aligned} \Lambda &= \sum_{\tilde{t}=1}^{\tilde{T}} \left(\mathbf{y}_{\tilde{t}} - \tilde{\mathbf{\Gamma}}' \mathbf{x}_{\tilde{t}} \right) \left(\mathbf{y}_{\tilde{t}} - \tilde{\mathbf{\Gamma}}' \mathbf{x}_{\tilde{t}} \right)' \\ &\leftrightarrow \tilde{\mathbf{T}} (\mathbf{C}_0 - \mathbf{B}_0' \mathbf{A}_0^{-1} \mathbf{B}_0) \end{aligned}$$

Del Negro and Schorfheide find that putting equal weights on prior and data ($\tilde{T} = T$) results in substantially better forecasts than unrestricted VAR, and better than Minnesota prior for horizons greater than 1 quarter.

RBC = good simplification (shrinkage).

Problem with Normal-Wishart prior

$$\boldsymbol{y} | \boldsymbol{\Omega}^{-1} \sim N \left(\begin{array}{ccc} \mathbf{m}, & \boldsymbol{\Omega} \otimes \mathbf{M} \\ nk \times 1 & n \times n & k \times k \end{array} \right)$$

$y_{1,t-1}$ = first element of \mathbf{x}_t

$y_{2,t-1}$ = second element of \mathbf{x}_t

$$\boldsymbol{\gamma} | \boldsymbol{\Omega}^{-1} \sim N \left(\begin{array}{c} \mathbf{m} \\ nk \times 1 \end{array}, \begin{array}{c} \boldsymbol{\Omega} \\ n \times n \end{array} \otimes \begin{array}{c} \mathbf{M} \\ k \times k \end{array} \right)$$

confidence in γ_1 = coefficient relating

y_{1t} to $y_{1,t-1}$ is $\sigma_{11} m_{11}$

confidence in γ_2 = coefficient relating

y_{1t} to $y_{2,t-1}$ is $\sigma_{11} m_{22}$

$$\boldsymbol{\gamma} | \boldsymbol{\Omega}^{-1} \sim N \left(\mathbf{m}, \boldsymbol{\Omega} \otimes \mathbf{M} \right)$$

$nk \times 1$ $n \times n$ $k \times k$

confidence in γ_{k+1} = coefficient relating

y_{2t} to $y_{1,t-1}$ is $\sigma_{22} m_{11}$

confidence in γ_{k+2} = coefficient relating

y_{2t} to $y_{2,t-1}$ is $\sigma_{22} m_{22}$

Problem: If $\sigma_{11}m_{11} > \sigma_{11}m_{22}$ (pretty confident variable 2 doesn't matter for variable 1), then must have $\sigma_{22}m_{11} > \sigma_{22}m_{22}$ (think variable 2 doesn't matter for variable 2 either)

Ways to get around this problem:

(1) Assume that Ω is diagonal. Then single-equation methods are equivalent to full-system inference, use different M_i for each equation.

(2) Drop natural conjugates, turn to numerical Bayesian methods.

II. Vector autoregressions

- A. Introduction
- B. Normal-Wishart priors for VARs
- C. Bayesian analysis of structural VARs

Consider structural VAR:

$$\begin{array}{ccccc} \mathbf{A}' & \mathbf{y}_t & = & \mathbf{B}' & \mathbf{x}_t + \mathbf{v}_t \\ n \times n & n \times 1 & & n \times k & k \times 1 \quad n \times 1 \end{array}$$

$$\mathbf{x}'_t = (\mathbf{y}'_{t-1}, \mathbf{y}'_{t-2}, \dots, \mathbf{y}'_{t-p}, 1)$$

$$k = np + 1$$

$$\mathbf{v}_t | \mathbf{y}_{t-1}, \mathbf{y}_{t-2}, \dots, \mathbf{y}_{-p+1} \sim N(\mathbf{0}, \mathbf{I}_n)$$

$$p(\mathbf{y}_t | \mathbf{y}_{t-1}, \mathbf{y}_{t-2}, \dots, \mathbf{y}_{-p+1})$$

$$= p(\mathbf{v}_t | \mathbf{y}_{t-1}, \mathbf{y}_{t-2}, \dots, \mathbf{y}_{-p+1}) \left| \frac{\partial \mathbf{y}_t}{\partial \mathbf{v}_t'} \right|^{-1}$$

$$\frac{\partial \mathbf{y}_t}{\partial \mathbf{v}_t'} = (\mathbf{A}')^{-1}$$

$$p(\mathbf{y}_1, \dots, \mathbf{y}_T | \mathbf{A}, \mathbf{B}; \mathbf{y}_0, \mathbf{y}_{-1}, \dots, \mathbf{y}_{-p+1})$$

$$= (2\pi)^{-Tn/2} |\mathbf{A}|^T$$

$$\exp \left[-\frac{1}{2} \sum_{t=1}^T (\mathbf{A}' \mathbf{y}_t - \mathbf{B}' \mathbf{x}_t)' (\mathbf{A}' \mathbf{y}_t - \mathbf{B}' \mathbf{x}_t) \right]$$

Take transpose

$$\mathbf{y}'_t \mathbf{A} = \mathbf{x}'_t \mathbf{B} + \mathbf{v}'_t$$

and stack rows on top of each other

for $t = 1, 2, \dots, T$:

$$\begin{array}{ccccc} \mathbf{Y} & \mathbf{A} & = & \mathbf{X} & \mathbf{B} & + & \mathbf{V} \\ T \times n & n \times n & & T \times k & k \times n & & T \times n \end{array}$$

$$\mathbf{B}_{k \times n} = \left[\mathbf{b}_1 \quad \cdots \quad \mathbf{b}_n \right]$$

$\mathbf{b}_i = (k \times 1)$ vector of coefficients

on the lags in the i th structural equation:

$$\mathbf{y}'_t \mathbf{a}_i = \mathbf{x}'_t \mathbf{b}_i + v_{it}$$

The vec operator stacks the columns of a $(k \times n)$ matrix on top of each other, from left to right, to form a $(kn \times 1)$ vector:

$$\text{vec}(\mathbf{B}) = \begin{bmatrix} \mathbf{b}_1 \\ \vdots \\ \mathbf{b}_n \end{bmatrix} \equiv \mathbf{b}$$

So first k elements of the $(nk \times 1)$ vector \mathbf{b} correspond to the coefficients on lags for the first equation in the VAR.

$$\mathbf{Y} \quad \mathbf{A} = \mathbf{X} \quad \mathbf{B} + \mathbf{V}$$

$T \times n \quad n \times n \quad T \times k \quad k \times n \quad T \times n$

$$\text{vec}(\mathbf{XB}) = (\mathbf{I}_n \otimes \mathbf{X}) \text{vec}(\mathbf{B})$$

$Tn \times 1 \quad n \times n \quad T \times k \quad k \times n$

$$= \tilde{\mathbf{X}} \quad \mathbf{b}$$

$Tn \times nk \quad nk \times 1$

for $\tilde{\mathbf{X}} \equiv (\mathbf{I}_n \otimes \mathbf{X})$

Likewise define

$$\begin{aligned}\tilde{\mathbf{y}} &\equiv \text{vec}(\mathbf{Y}\mathbf{A}) \\ Tn \times 1 & \\ &= (\mathbf{I}_n \otimes \mathbf{Y})\mathbf{a}\end{aligned}$$

for $\mathbf{a} \equiv \text{vec}(\mathbf{A})$. First n elements of \mathbf{a}
 $n^2 \times 1$

correspond to coefficients on contemporaneous variables in first equation of VAR.

$$\begin{matrix} \mathbf{Y} & \mathbf{A} & = & \mathbf{X} & \mathbf{B} & + & \mathbf{V} \\ T \times n & n \times n & & T \times k & k \times n & & T \times n \end{matrix}$$

Taking vec of full system,

$$\tilde{\mathbf{y}} = \tilde{\mathbf{X}}\mathbf{b} + \tilde{\mathbf{v}}$$

where $\tilde{\mathbf{v}} \sim N(\mathbf{0}, \mathbf{I}_{Tn})$. Note that conditional on \mathbf{a} , this is a classical regression model with unit variance for the residual.

$$p(\mathbf{Y}|\mathbf{a}, \mathbf{b}) = (2\pi)^{-Tn/2} |\mathbf{A}|^T \exp\left[-\frac{1}{2} (\tilde{\mathbf{y}} - \tilde{\mathbf{X}}\mathbf{b})' (\tilde{\mathbf{y}} - \tilde{\mathbf{X}}\mathbf{b})\right]$$

$$\mathbf{b}|\mathbf{a} \sim N(\mathbf{m}(\mathbf{a}), \mathbf{M}(\mathbf{a}))$$

$$p(\mathbf{b}|\mathbf{a}) = (2\pi)^{-nk/2} |\mathbf{M}(\mathbf{a})|^{-1/2} \exp\left\{-\frac{1}{2} [\mathbf{b} - \mathbf{m}(\mathbf{a})]' [\mathbf{M}(\mathbf{a})]^{-1} [\mathbf{b} - \mathbf{m}(\mathbf{a})]\right\}$$

$p(\mathbf{a})$ arbitrary

$$p(\mathbf{b}, \mathbf{a}|\mathbf{Y}) = p(\mathbf{b}|\mathbf{a}, \mathbf{Y})p(\mathbf{a}|\mathbf{Y})$$

$$\mathbf{b}|\mathbf{a}, \mathbf{Y} \sim N(\mathbf{m}^*(\mathbf{a}), \mathbf{M}^*(\mathbf{a}))$$

$$\mathbf{M}^*(\mathbf{a}) = \left\{ [\mathbf{M}(\mathbf{a})]^{-1} + \tilde{\mathbf{X}}' \tilde{\mathbf{X}} \right\}^{-1}$$

$$\tilde{\mathbf{X}} \equiv (\mathbf{I}_n \otimes \mathbf{X})$$

$$\mathbf{M}^*(\mathbf{a}) = \left\{ [\mathbf{M}(\mathbf{a})]^{-1} + [\mathbf{I}_n \otimes \mathbf{X}' \mathbf{X}] \right\}^{-1}$$

$$\mathbf{b}|\mathbf{a}, \mathbf{Y} \sim N(\mathbf{m}^*(\mathbf{a}), \mathbf{M}^*(\mathbf{a}))$$

$$\mathbf{m}^*(\mathbf{a}) = \mathbf{M}^*(\mathbf{a}) \left\{ [\mathbf{M}(\mathbf{a})]^{-1} \mathbf{m}(\mathbf{a}) + \tilde{\mathbf{X}}' \tilde{\mathbf{y}} \right\}$$

$$\begin{aligned} \tilde{\mathbf{X}}' \tilde{\mathbf{y}} &= (\mathbf{I}_n \otimes \mathbf{X}') (\mathbf{I}_n \otimes \mathbf{Y}) \mathbf{a} \\ &= (\mathbf{I}_n \otimes \mathbf{X}' \mathbf{Y}) \mathbf{a} \end{aligned}$$

Still, we need to “invert” $(nk \times nk)$ matrix

$$\{[\mathbf{M}(\mathbf{a})]^{-1} + [\mathbf{I}_n \otimes \mathbf{X}'\mathbf{X}]\}^{-1}$$

Suppose our prior for equation i takes the form

$$\mathbf{b}_{i|\mathbf{a}} \sim N(\mathbf{m}_i(\mathbf{a}), \mathbf{M}_i(\mathbf{a}))$$

for $\mathbf{M}_i(\mathbf{a})$ a $(k \times k)$ matrix, with priors independent across equations.

$$\{[\mathbf{M}(\mathbf{a})]^{-1} + [\mathbf{I}_n \otimes \mathbf{X}'\mathbf{X}]\}^{-1}$$

$$= \left\{ \begin{bmatrix} \mathbf{M}_1(\mathbf{a})^{-1} & \dots & \mathbf{0} \\ \vdots & \vdots & \vdots \\ \mathbf{0} & \dots & \mathbf{M}_n(\mathbf{a})^{-1} \end{bmatrix} + \begin{bmatrix} \mathbf{X}'\mathbf{X} & \dots & \mathbf{0} \\ \vdots & \vdots & \vdots \\ \mathbf{0} & \dots & \mathbf{X}'\mathbf{X} \end{bmatrix} \right\}^{-1}$$

$$\left\{ [\mathbf{M}(\mathbf{a})]^{-1} + [\mathbf{I}_n \otimes \mathbf{X}'\mathbf{X}] \right\}^{-1}$$

$$= \begin{bmatrix} \mathbf{M}_1^*(\mathbf{a}) & \cdots & \mathbf{0} \\ \vdots & \vdots & \vdots \\ \mathbf{0} & \cdots & \mathbf{M}_n^*(\mathbf{a}) \end{bmatrix}$$

for $\mathbf{M}_i^*(\mathbf{a}) = [\mathbf{M}_i(\mathbf{a})^{-1} + \mathbf{X}'\mathbf{X}]^{-1}$

$$\mathbf{m}^*(\mathbf{a}) = \mathbf{M}^*(\mathbf{a}) \{ [\mathbf{M}(\mathbf{a})]^{-1} \mathbf{m}(\mathbf{a}) + (\mathbf{I}_n \otimes \mathbf{X}'\mathbf{Y})\mathbf{a} \}$$

$$\begin{bmatrix} \mathbf{m}_1^*(\mathbf{a}) \\ \vdots \\ \mathbf{m}_n^*(\mathbf{a}) \end{bmatrix} = \begin{bmatrix} \mathbf{M}_1^*(\mathbf{a})\mathbf{q}_1(\mathbf{a}) \\ \vdots \\ \mathbf{M}_n^*(\mathbf{a})\mathbf{q}_n(\mathbf{a}) \end{bmatrix}$$

$$\mathbf{q}_i(\mathbf{a}) = [\mathbf{M}_i(\mathbf{a})]^{-1} \mathbf{m}_i(\mathbf{a}) + \mathbf{X}'\mathbf{Y}\mathbf{a}_i$$

Specification of $p(\mathbf{b}|\mathbf{a})$:

expect each series to behave
like a random walk.

Structural equations:

$$\begin{array}{ccccc} \mathbf{Y} & \mathbf{A} & = & \mathbf{X} & \mathbf{B} + \mathbf{V} \\ T \times n & n \times n & & T \times k & k \times n \quad T \times n \end{array}$$

Reduced form:

$$\begin{array}{ccccc} \mathbf{Y} & = & \mathbf{X} & \mathbf{\Pi} & + \mathbf{E} \\ T \times n & & T \times k & k \times n & T \times n \end{array}$$

$$\mathbf{\Pi} = \mathbf{B}\mathbf{A}^{-1}$$

$$\mathbf{E} = \mathbf{V}\mathbf{A}^{-1}$$

Random walk:

$$\Pi_{k \times n} = \begin{bmatrix} \mathbf{I}_n \\ \mathbf{0} \\ \vdots \\ \mathbf{0} \end{bmatrix} = \mathbf{B}_{k \times n} \mathbf{A}^{-1}_{n \times n}$$

$$E(\mathbf{B}|\mathbf{A}) = \begin{bmatrix} \mathbf{A} \\ \mathbf{0} \\ \vdots \\ \mathbf{0} \end{bmatrix}$$

$$\mathbf{b}_i | \mathbf{a} \sim N(\mathbf{m}_i(\mathbf{a}), \mathbf{M}_i(\mathbf{a}))$$

$$\mathbf{m}_i(\mathbf{a}) = \begin{bmatrix} \mathbf{a}_i \\ \mathbf{0} \\ \vdots \\ \mathbf{0} \end{bmatrix}$$

Let $m_i^{(r)}$ denote the r th element of this vector (prior expectation of r th element of \mathbf{b}_i) and $M_i^{(r)}$ its variance:

$$b_i^{(r)} | \mathbf{a} \sim N(m_i^{(r)}, M_i^{(r)})$$

with priors across coefficients taken to be independent.

Multiplying the likelihood by the prior density

$$p(b_i^{(r)} | \mathbf{a}) = (2\pi)^{-1/2} [M_i^{(r)}]^{-1/2} \exp \left[-\frac{[b_i^{(r)} - m_i^{(r)}]^2}{2M_i^{(r)}} \right]$$

is numerically identical to acting as if I had observed a variable $q_i^{(r)}$ from the system

$$q_i^{(r)} = b_i^{(r)} / \sqrt{M_i^{(r)}} + v_i^{(r)}$$

where the observed value of $q_i^{(r)}$ is

$$m_i^{(r)} / \sqrt{M_i^{(r)}} \text{ and } v_i^{(r)} \sim N(0, 1).$$

Or, since $m_i^{(r)}$ is the r th element of \mathbf{a}_i if $r \leq n$ and is zero otherwise, this is numerically identical to having observed the $(n \times 1)$ vector $\mathbf{y}_i^{(r)}$ and $(k \times 1)$ vector $\mathbf{x}_i^{(r)}$ from the following system:

$$[\mathbf{y}_i^{(r)}]' \mathbf{a}_i = [\mathbf{x}_i^{(r)}]' \mathbf{b}_i + v_i^{(r)}$$

$$\mathbf{y}_i^{(r)} = \begin{cases} \mathbf{e}_r(n) / \sqrt{M_i^{(r)}} & \text{if } r \leq n \\ \mathbf{0} & \text{otherwise} \end{cases}$$

$$\mathbf{x}_i^{(r)} = \mathbf{e}_r(k) / \sqrt{M_i^{(r)}}$$

for $\mathbf{e}_r(n)$ the r th column of \mathbf{I}_n

$\mathbf{e}_r(k)$ the r th column of \mathbf{I}_k

Stack these “dummy observations”

for $r = 1, 2, \dots, k$ in matrices

$$\mathbf{Y}_{id} = \begin{bmatrix} [\mathbf{y}_i^{(1)}]' \\ \vdots \\ [\mathbf{y}_i^{(k)}]' \end{bmatrix} \quad \mathbf{X}_{id} = \begin{bmatrix} [\mathbf{x}_i^{(1)}]' \\ \vdots \\ [\mathbf{x}_i^{(k)}]' \end{bmatrix}$$

$k \times n$ $k \times k$

The posterior $p(\mathbf{b}_i|\mathbf{a}, \mathbf{Y})$ is then:

$$\mathbf{b}_i|\mathbf{a}, \mathbf{Y} \sim N(\mathbf{m}_i^*(\mathbf{a}), \mathbf{M}_i^*(\mathbf{a}))$$

$$\begin{aligned}\mathbf{M}_i^*(\mathbf{a}) &= [\mathbf{M}_i(\mathbf{a})^{-1} + \mathbf{X}'\mathbf{X}]^{-1} \\ &= (\mathbf{X}'_{id}\mathbf{X}_{id} + \mathbf{X}'\mathbf{X})^{-1}\end{aligned}$$

$$\begin{aligned}\mathbf{m}_i^*(\mathbf{a}) &= \mathbf{M}_i^*(\mathbf{a}) \{[\mathbf{M}_i(\mathbf{a})]^{-1}\mathbf{m}_i(\mathbf{a}) + \mathbf{X}'\mathbf{Y}\mathbf{a}_i\} \\ &= (\mathbf{X}'_{id}\mathbf{X}_{id} + \mathbf{X}'\mathbf{X})^{-1} (\mathbf{X}'_{id}\mathbf{Y}_{id} + \mathbf{X}'\mathbf{Y})\mathbf{a}_i\end{aligned}$$

$$b_i^{(r)} | \mathbf{a} \sim N(m_i^{(r)}, M_i^{(r)})$$

Remaining question: how choose $M_i^{(r)}$.

Let $j(r)$ denote which variable the r th coefficient refers to ($j = 1, 2, \dots, n$)

and $\ell(r)$ its lag ($\ell = 1, 2, \dots, p$)

i.e., $b_i^{(r)}$ is the coefficient relating

$\mathbf{y}'_t \mathbf{a}_i$ to $y_{j,t-\ell}$

(1) If units in which y_{jt} is measured are doubled, value of $b_i^{(r)}$ is cut in half

\Rightarrow make $\sqrt{M_i^{(r)}}$ inversely proportional to σ_j , the standard deviation of univariate autoregression for y_{jt}

(2) have more confidence in zero priors
for bigger ℓ

\Rightarrow make $\sqrt{M_i^{(r)}}$ inversely proportional to ℓ^{λ_3}

$(\lambda_3 > 0)$

$$b_i^{(r)} | \mathbf{a} \sim N(m_i^{(r)}, M_i^{(r)})$$

$$\sqrt{M_i^{(r)}} = \begin{cases} \frac{\lambda_0 \lambda_1}{\sigma_{j(r)} [\ell(r)]^{\lambda_3}} & \text{for } r = 1, 2, \dots, k-1 \\ \lambda_0 \lambda_4 & \text{for } r = k \end{cases}$$

where λ_0 controls tightness of prior for \mathbf{a}
and λ_1 controls tightness of random walk
prior

Distribution of \mathbf{a}

$$p(\mathbf{a}, \mathbf{b}|\mathbf{Y}) = p(\mathbf{b}|\mathbf{a}, \mathbf{Y})p(\mathbf{a}|\mathbf{Y})$$

$$\mathbf{b}|\mathbf{a}, \mathbf{Y} \sim N(\mathbf{m}^*(\mathbf{a}), \mathbf{M}^*(\mathbf{a}))$$

$$p(\mathbf{a}|\mathbf{Y}) \propto p(\mathbf{a})|\mathbf{A}|^T$$

$$\begin{aligned} & |\mathbf{I}_{Tn} + (\mathbf{I}_n \otimes \mathbf{X})\mathbf{M}(\mathbf{a})(\mathbf{I}_n \otimes \mathbf{X}')|^{-1/2} \\ & \exp \left\{ -\frac{1}{2} [\mathbf{a}'(\mathbf{I}_n \otimes \mathbf{Y}'\mathbf{Y})\mathbf{a} + \right. \\ & \quad + \mathbf{m}(\mathbf{a})'\mathbf{M}(\mathbf{a})^{-1}\mathbf{m}(\mathbf{a}) \\ & \quad \left. - \mathbf{m}^*(\mathbf{a})'(\mathbf{M}^*(\mathbf{a}))^{-1}\mathbf{m}^*(\mathbf{a})] \right\} \end{aligned}$$

What is this distribution $p(\mathbf{a}|\mathbf{Y})$?

Use numerical methods.

Example: Sims-Zha, distribution

of $p(\mathbf{a}|\mathbf{Y})$:

$$p(\mathbf{a}|\mathbf{Y}) \propto p(\mathbf{a})|\mathbf{A}|^T$$

$$|\mathbf{I}_{Tn} + (\mathbf{I}_n \otimes \mathbf{X})\mathbf{M}(\mathbf{a})(\mathbf{I}_n \otimes \mathbf{X}')|^{-1/2}$$

$$\exp \left\{ -\frac{1}{2} [\mathbf{a}' (\mathbf{I}_n \otimes \mathbf{Y}'\mathbf{Y})\mathbf{a} + \right.$$

$$+ \mathbf{m}(\mathbf{a})' \mathbf{M}(\mathbf{a})^{-1} \mathbf{m}(\mathbf{a})$$

$$\left. - \mathbf{m}^*(\mathbf{a})' (\mathbf{M}^*(\mathbf{a}))^{-1} \mathbf{m}^*(\mathbf{a})] \right\}$$

$$\equiv q(\mathbf{a})$$

Importance density $g(\mathbf{a})$ should be similar to $q(\mathbf{a})$ but with fatter tails.

(1) Find

$$\mathbf{a}_0 \equiv \arg \max_{\mathbf{a}} q(\mathbf{a})$$

$$\mathbf{H}_0 \equiv - \frac{\partial^2 \log q(\mathbf{a})}{\partial \mathbf{a} \partial \mathbf{a}'} \Big|_{\mathbf{a}=\mathbf{a}_0}$$

(2) Let $g(\mathbf{a})$ be n^2 -dimensional Student t-distribution centered at \mathbf{a}_0 with scale matrix \mathbf{H}_0^{-1} and 9 degrees of freedom.

(3) Generate j th draw $\mathbf{a}^{(j)}$ from $g(\mathbf{a})$.

E.g., generate

$$\mathbf{u}^{(j)} \sim N(\mathbf{0}, \mathbf{I}_{n^2})$$

$$\mathbf{v}^{(j)} = \mathbf{P}_0^{-1} \mathbf{u}^{(j)} + \mathbf{a}_0$$

\mathbf{P}_0 is Cholesky factor of \mathbf{H}_0

$$\mathbf{e}^{(j)} \sim N(\mathbf{0}, \mathbf{I}_9)$$

$$\mathbf{v}^{(j)} = (1/9) [\mathbf{e}^{(j)}]' [\mathbf{e}^{(j)}]$$

$$\mathbf{a}^{(j)} = \mathbf{v}^{(j)} / \sqrt{\mathbf{v}^{(j)}}$$

(4) Calculate

$$g(\mathbf{a}^{(j)}) =$$

$$c \left\{ 1 + [\mathbf{a}^{(i)} - \mathbf{a}_0]' \mathbf{H}_0^{-1} [\mathbf{a}^{(i)} - \mathbf{a}_0] \right\}^{-(n^2+9)/2}$$

choosing c so that $\max_{j=1,\dots,D} g(\mathbf{a}^{(j)})$ is same

scale as $\max_{j=1,\dots,D} q(\mathbf{a}^{(j)})$

(5) Calculate the weight

$$\omega^{(j)} = \frac{q(\mathbf{a}^{(j)})}{g(\mathbf{a}^{(j)})}$$

(6) Repeat steps (3)-(5) for

$$j = 1, 2, \dots, D.$$

(7) The sample $\mathbf{a}^{(1)}, \dots, \mathbf{a}^{(D)}$, when weighted by $K^{-1}\omega^{(1)}, \dots, K^{-1}\omega^{(D)}$ for $K = \omega^{(1)} + \dots + \omega^{(D)}$, is a sample from $p(\mathbf{a}|\mathbf{Y})$, e.g.,

$$\hat{E}(\mathbf{a}|\mathbf{Y}) = \frac{\sum_{j=1}^D \omega^{(j)} \mathbf{a}^{(j)}}{\sum_{j=1}^D \omega^{(j)}}$$

(8) For each j , generate $\mathbf{b}^{(j)}$ from the $N(\mathbf{m}^*(\mathbf{a}^{(j)}), \mathbf{M}^*(\mathbf{a}^{(j)}))$ distribution and weight with $K^{-1}\omega^{(j)}$ for a draw from $p(\mathbf{b}|\mathbf{Y})$, e.g.

$$\hat{E}(\mathbf{b}|\mathbf{Y}) = \frac{\sum_{j=1}^D \omega^{(j)} \mathbf{b}^{(j)}}{\sum_{j=1}^D \omega^{(j)}}$$